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The Carotron CTCW (Constant Tension Center Wind) Control is designed for use with a torque mode drive to provide constant tension or taper tension control of a center driven winder. Web tension is regulated by controlling motor torque through varying levels of material roll diameter, line speed and line acceleration rate. These diameter, friction and inertia compensating torque signals are summed with other torque signals to further provide control of core tension, taper tension, stall tension and even Winder motor RPM when in the JOG mode.

The CTCW can accept an external diameter signal or can calculate diameter from Line and Winder speed signals by an internal Radius Computer with memory. A +10 VDC reference is available for a direct contact rider roll compensator to measure diameter. The Line Speed signal input is isolated to allow use of existing feedback or process tachometers.

#### **Standard Features**

• Provides constant tension or taper tension torque reference to a torque mode drive based on the following:

- Core tension, minimum torque

- Taper tension, change in tension as roll builds

- Diameter compensation, increase torque with roll build

- Friction compensation, torque increases with line speed

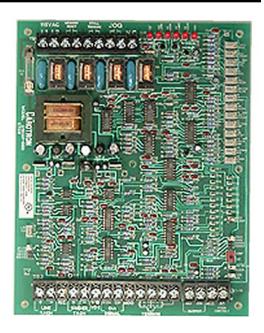
- Inertia compensation, torque increases with line acceleration rate

- Stall tension, parking torque selectable by contact closure

Torque reference output is +10 VDC maximum
Isolated line speed input for up to 240 VDC as signal input to radius computer and inertia compensation circuits

# **Constant Tension Center Wind Control Card CTCW**

### Model D10337-000



 Accepts the following for diameter compensation
 Line speed signal and winder speed signal to calculate roll radius on board and store in 8 bit digital memory

- Externally generated signal from a sonic or optical sensor, +10 VDC max. at full diameter

- Direct contact rider roll compensator to measure roll diameter. A +10 VDC reference is supplied to source a potentiometer
- Maximum roll build range is 10 to 1
- On-board velocity loop for jog speed control using armature voltage feedback that is selectable for 90 or 180 VDC
- 20 turn cermet calibration potentiometers

• On-board 115 VAC relays allow contact closures from external logic to select jog, stall tension or memory reset functions

### Specifications

A.C. INPUT

115 VAC, 50/60 Hz, 11VA max., internally fused

#### SIGNAL INPUTS

- Line speed signal, isolated, 240 VDC maximum in four ranges
- Winder speed signal, 240 VDC maximum in four ranges
- Diameter signal, +10 VDC maximum
- Tension pot. input, 1K ohm minimum resistance
- Winder armature signal, 90 and 180 VDC ranges

#### **BUILD RANGE**

• 10 to 1

#### CORE 100%-WINDER WINDER RADIUS TORQUE SPEED % % 90 CORE 10 50 33 25 2× CORE 20 3× CORE 30 80 4× CORE 40 5× CORE 20 50 16.7 60 6× CORE 14.3 70 7× CORE 70 8× CORE 80 90 9× CORE 11.1 SPEED 10 100 10× CORE 60 2× CORE - CONSTANT TENSION 50-WINDER ----- TAPER TENSION 40 3× CORE 4× CORE 5× CORE 30 6× CORE 7× CORE 8× CORE 20-9× CORE 10× CORE 10 0 10 20 30 40 50 60 70 80 90 0 100% Fig. C.17

#### SPEED/TORQUE CURVES FOR CTCW CONTROL

#### CONTROL RELAYS

• Jog relay, 115 VAC @ .1VA, customer contact required

Stall tension relay, 115 VAC @ .1 VA, customer contact required

Memory reset relay, 115 VAC @ .1 VA, customer contact required

#### SIGNAL OUTPUTS

Torque mode -10 VDC maximum torque reference

• Jog mode -3 VDC maximum, closed loop speed reference equivalent to 500 RPM motor speed, adjustable

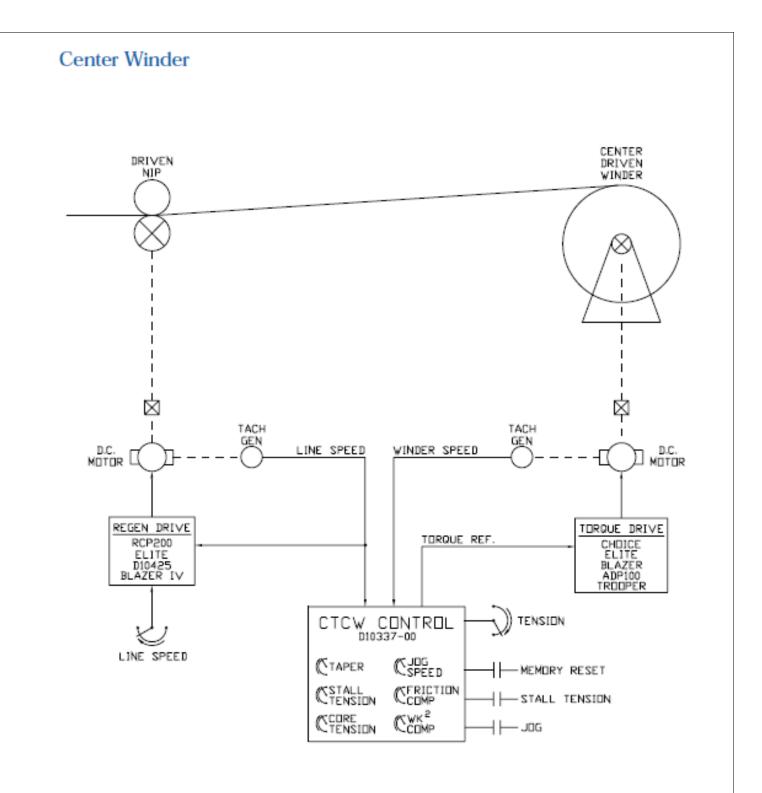
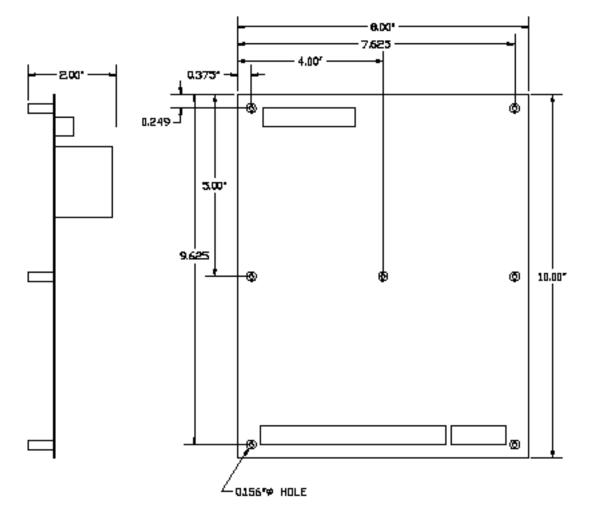
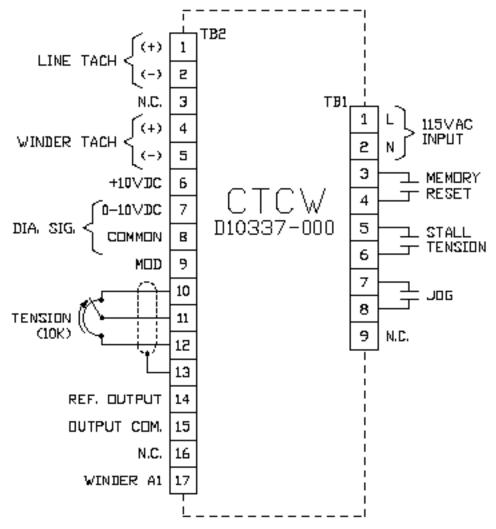


Fig. C.18

## Dimensions



### Connections



## Constant Tension Center Wind Control Card (CTCW) Model D10337-000

View or download the complete D10337-000 Instruction Manual (MAN 1022-00) from www.carotron.com .



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