

MicroManager
MM3000 Series
Dedicated Modular Controllers

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## MM3000-CRG MM3000-PID MM3000-CTCW

The MicroManager 3000 Series is a microprocessor based industrial system controller designed to handle a wide range of applications. The simple user interface allows high level microprocessor control of an application but without the need of a computer for configuration. Modbus® communication provides simple linking to HMI touch screens and other networked devices.

Model MM3000-CRG (Center Reference Generator) is designed for velocity mode winding applications and for torque mode winding/unwinding applications. In the velocity mode, the winder sets/controls the line speed. The MicroManager calculates the required center driven takeup speed to maintain the desired line speed. The MM3000-CRG can also be used on torque mode winders and unwinders (brake and driven).

Model MM3000-PID (Proportional-Integral-Derivative) is designed for velocity mode applications that use dancers or loadcells. In addition, the unit can also be used as a generic PID controller. In winding/unwinding applications, the MM3000-PID also uses internal algorithms to determine the required center driven speed based on roll diameter.

Model MM3000-CTCW (Constant Tension Center Winder) is designed for use with a torque mode drive to provide constant tension or taper tension control of a center driven winder. Web tension is regulated by controlling motor torque through varying levels of material roll diameter, line speed, and line acceleration. These diameter, friction, and inertia compensating torque signals can also be used with an optional loadcell feedback signal to provide closed loop tension control.

The Modbus RS485 communications port allows for all parameters to be read and for selected parameters to be changed. Limited programming capability is also available

# **Electrical Specifications**

## A.C. Input Voltage Range - Single Phase

- 115 VAC  $\pm$  10%, 50/60 Hz  $\pm$  2 Hz
- Fused internally

#### **Power Supply Output**

+12V regulated, 70mA max.

## **Digital Inputs (4 Total)**

- Selectable Sinking or Sourcing Logic
- Vil=+10.5 VDC min to +12.0 VDC max
- Vih=0.0 VDC min to +8.5 VDC max

#### **Analog Inputs (2 Total)**

- 10 bit resolution (over-sampled to achieve 12 bit)
- Voltage Range: 0 to +12 VDC
- Input Impedance: 240kΩ

#### **Frequency Inputs (1 Total)**

- Frequency: 42kHz max, square wave (sink or source)
- Voltage: +12 VDC max

Vil=0.0 VDC min to +1.5 VDC max Vih=+2.5 VDC min to +12.0 VDC max

# Digital Outputs (2 Total)

- Open collector (sinking output)
- 100ma max, 30VDC max

#### **Analog Outputs (3 Total)**

Outputs 1 & 2:

12 bits, voltage 0 to +10 VDC max, or current 0 to +20 mADC max

• Output 3:

10 bits, voltage only 0 to + 5 VDC max

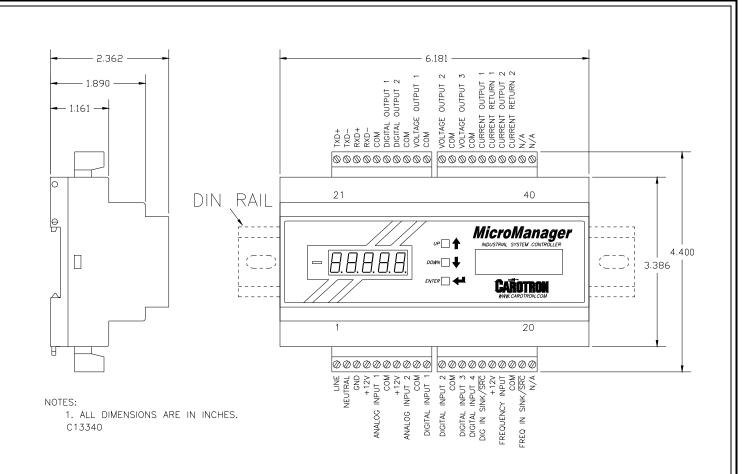
 Output with respect to roll diameter is linear in Torque Mode and hyperbolic in Velocity Mode

## **Communications**

• Modbus RTU RS485 Multidrop (2 or 4 wire)

## **Temperature Range**

Chassis: 0-55°C



# MicroManager MM3000 Series

Physical Specifications: 4.400"H x 6.181W x 2.362"D

Shipping Weight: 2 lbs.

View or download the complete MicroManager Instruction Manuals from www.carotron.com.



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